1) Make a sketch using getPhoto() to control the LED using proportional control. Here is an outline:
a. Set out=0;
b. Loop for $k=1$ to 100
c. Set analogWrite() to out
d. Wait 100 ms .
e. Measure V using getPhoto
f. Serial.println V
g. Define err ie $e=V$ set-V;
h. Define out=P*e;
i. Make sure out is between [0 255].
j. Serial.println e and out
k. End loop
2) Find the largest value of $\mathrm{P}=$ Pmax that does not causes the V to oscillate. How does it compare to your estimate from part I?
3) What is the value of the error for the largest $P$ that will not oscillate?
4) Plot V and out verses step k from above for Pmax, Pmax/2, and Pmax/10.
5) Add Integral control. Initialize es to 0 before the loop and after line g above add es=es+e; Then change line $h$ to out= $P^{*} e+l^{*}$ es.
6) Find values of $\mathrm{P}=\mathrm{P} 0$ and $\mathrm{I}=\mathrm{IO}$ that give good control.
7) Plot V and out verses step $k$ for ( $\mathrm{P} 0, \mathrm{IO}$ ), ( $\mathrm{P} 0, \mathrm{I} 0 / 10$ ), ( $\mathrm{P} 0 / 10, \mathrm{IO}$ ), and ( $\mathrm{P} 0 / 10,10 / 10$ ). You may have to lengthen the k loop to see the full effects. Give a brief explanation of the plots.
