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Physics 35100 Mechanics
October 31, 2022

## Exam 1-retake

## Show all of your work!

Question 1. What is your name?
Question 2. Driven Oscillator A block of mass $m$ is resting on a friction-less table and connected to a movable wall by a linear spring with spring constant $K$ and rest length $L$ so that force is zero if $x-P(t)=L$. It is confined to move in one dimension. Initially the mass is not moving and positioned so the spring is at its rest length. The wall's position $P$ oscillates according to $P(t)=P_{0} \sin (\omega t)$.

(1) In terms of the position $x$, what is the equation of motion.
(2) Consider the mass-spring system:
(a) What is the kinetic, potential, and total energy at $t=0$ ?
(b) Is total energy conserved? Why? Why not?
(c) Is momentum conserved? Why? Why not?
(3) Non-dimensionalize the equation using $[L]=L,[M]=m$, and $[T]=\frac{1}{\omega_{0}}$, where $\omega_{0}=\sqrt{\frac{K}{m}}$ to obtain an equation of motion of the form:

$$
\ddot{u}=-u+A_{0} \sin (\Omega \tau),
$$

where $\tau=\omega_{0} t$ and $u=\frac{x-L}{L}$. Find the values of $A_{0}$ and $\Omega$.
(4) Show that:

$$
u(\tau)=A \sin (\tau)+B \sin (\Omega \tau)
$$

solves the equation:

$$
\ddot{u}=-u+A_{0} \sin (\Omega \tau),
$$

Find the values of $A$ and $B$ for the conditions above.
(5) Find the impulse $J$ over 1 period of the drive $0 \leq t \leq 2 \pi / \omega$ ?

Question 3. Roller coaster A car of mass $M$ rides on a friction-less three-dimensional track. The track has a circular footprint of radius $R$ such that the $x$ and $y$ coordinates form a circle $x^{2}+y^{2}=R^{2}$ in the plane of the ground. The height $z$ of the track varies with the angle $\theta$ around the $\operatorname{circle} z(\theta)=H(1-\cos \theta)$.

(1) Find the Lagrangian in terms of $\theta$ and $\dot{\theta}$.
(2) Find the generalized momentum $p_{\theta}$.
(3) Find the equation of motion.
(4) Find the Hamiltonian $H$ as a function of $\dot{\theta}$ and $\theta$. Then express it in terms of $p_{\theta}$ and $\theta$ by eliminating $\dot{\theta}$. Is $p_{\theta}$ or $H$ conserved? Why or Why not?

Question 4. Hamilton's Equations of Motion The Hamiltonian $H\left(q_{k}, p_{k}, t\right)$ is a function of $K$ generalized coordinates $q_{k}, K$ generalized momenta,

$$
p_{k}=\frac{\partial L}{\partial \dot{q}_{k}},
$$

and time $t$, where $L$ is the Lagrangian. The Lagrangian $L\left(q_{k}, \dot{q}_{k}, t\right)$ is a function of $K$ generalized coordinates $q_{k}, K$ generalized velocities $\dot{q}_{k}$, and time $t$. The Hamiltonian is related to the Lagrangian by this transformation:

$$
H\left(q_{k}, p_{k}, t\right)=\sum_{k=1}^{K} p_{k} \dot{q}_{k}-L\left(q_{k}, \dot{q}_{k}, t\right)
$$

The total differential $d F$ of any function $F(x, . ., z)$ is

$$
d F=\frac{\partial F}{\partial x} d x+\ldots+\frac{\partial F}{\partial z} d z
$$

Find the total differential of the transformation equation and use the Euler-Lagrange equations and definition of $p_{k}$ to show that:

$$
\dot{p}_{k}=-\frac{\partial H}{\partial q_{k}}, \quad \quad \dot{q}_{k}=\frac{\partial H}{\partial p_{k}}, \quad \frac{\partial H}{\partial t}=-\frac{\partial L}{\partial t} .
$$

These are a set of first order differential equations of motion called Hamilton's equations. (Hint: If differentials like $d x, d y$, etc are independent so if $A d x+B d y+\ldots+C d z=0$, then $A=0$ and $B=0$, etc.)

Question 5. Time dependent Motion. A particle of mass $m=3 \mathrm{~kg}$ is initially $t=0 \mathrm{~s}$ at position $\vec{x}(0)=(-2,0,3) m$. The particle has a velocity

$$
\dot{\vec{x}}(t)=(\exp (-t / 3),-t,-2 \cos t) \mathrm{m} / \mathrm{s}
$$

(1) Find a general expression for the position of the particle $\vec{x}(t)$ and the acceleration $\ddot{x}(t)$ as functions of time $t$.
(2) What time $t$ is the $\hat{z}=(0,0,1)$ component of the acceleration $a_{z}=\ddot{\vec{x}} \cdot \hat{z}$ maximum in the range of $0 s \leq t \leq 6 s$ ? What is the position vector at that point?

Question 6. Springy blocks on a wedge Two blocks of mass $m_{1}$ and $m_{2}$ are connected together by a massless linear spring with spring constant K and sit on a friction-less wedge with angle $\theta$. When $x_{2}-x_{1}=L$ the spring produces no force. The wedge can not move. The blocks are free to move under the force of gravity pointing downward.

(1) Find the accelerations of the blocks $\ddot{x}_{1}$ and $\ddot{x}_{2}$. Note any conserved quantities.
(2) Find the acceleration of the center of mass of the blocks $\ddot{X}_{c m}$ and the acceleration of generalized coordinate that measures the distance between the blocks $\ddot{u}=\ddot{x}_{2}-\ddot{x}_{1}$.

